Multifunctional damper actuator for adjusting air dampers in ventilation and air-conditioning systems for building services installations

- For air dampers up to approx. $4 \mathrm{~m}^{2}$
- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control: Modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable



## Technical data

Electrical data

| Nominal voltage | AC $24 \mathrm{~V}, 50 / 60 \mathrm{~Hz} / \mathrm{DC} 24 \mathrm{~V}$ |  |  |
| :---: | :---: | :---: | :---: |
| Nominal voltage range | AC 19.2 ... $28.8 \mathrm{~V} / \mathrm{DC} 21.6$... 28.8 V |  |  |
| Power consumption In operation At rest For wire sizing | 4 W @ nominal torque 1.25 W <br> 6 VA |  |  |
| Connection | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |  |  |
| Functional data | Factory settings | Variable | Settings |
| Torque (nominal torque) | Min. 20 Nm @ nominal voltage | 25\%, 50\%, $75 \%$ reduziert |  |
| Control Control signal Y | DC $0 \ldots 10 \mathrm{~V}$, input impedance $100 \mathrm{k} \Omega$ | Open-close, 3-point (AC only), modulating (DC $0 \ldots 32 \mathrm{~V}$ ) |  |
| Operating range | DC $2 \ldots 10 \mathrm{~V}$ | Start point DC $0.5 \ldots 30 \mathrm{~V}$ <br> End point DC $2.5 \ldots 32 \mathrm{~V}$ |  |
| Position feedback (Measuring voltage U) | DC $2 \ldots . .10 \mathrm{~V}$, max. 0.5 mA | Start point DC $0.5 \ldots 8 \mathrm{~V}$ <br> End point DC $2.5 \ldots 10 \mathrm{~V}$ |  |
| Position accuracy | $\pm 5 \%$ |  |  |
| Direction of rotation | Reversible with switch 0 / 1 |  |  |
| Direction of motion at $\mathrm{Y}=0 \mathrm{~V}$ | In switch position $0 \curvearrowleft$ resp. $1 \curvearrowright$ | Electronically reversible |  |
| Manual override | Gearing latch disengaged with pushbutton, can be locked |  |  |
| Angle of rotation | Max. $95^{\circ} \varangle$, can be limited at both ends with adjustable mechanical end stops |  |  |
| Running time | $150 \mathrm{~s} / 90^{\circ} \Varangle$ | $86 . . .346$ s |  |
| Automatic adjustment running time, operating range and measuring signal U to match the mechanical angle of rotation | Manual triggering of the adaption by pressing the «Adaption» button or with the PC-Tool | Automatic adaption whenever the supply voltage is switched on, or manual triggering |  |
| Override control | $\begin{array}{ll}\text { MAX (maximum position) } & =100 \% \\ \text { MIN (minimum position) } & =0 \% \\ \text { ZS (intermediate position, AC only) } & =50 \%\end{array}$ | $\begin{aligned} & \text { MAX }=\left(\text { MIN }+30^{\circ} \Varangle\right) \ldots 100 \% \\ & \text { MIN }=0 \% \ldots\left(\text { MAX }-30^{\circ} \Varangle\right) \\ & Z S=\text { MIN } \ldots \text { MAX } \end{aligned}$ |  |
| Sound power level | Max. 45 dB (A) | With a $\quad 86 \mathrm{~s}=45 \mathrm{~dB}(\mathrm{~A})$ running time $346 \mathrm{~s}=<35 \mathrm{~dB}(\mathrm{~A})$ |  |
| Position indication | Mechanical, pluggable |  |  |
| Safety |  |  |  |
| Protection class | III Safety extra-low voltage / UL Class 2 Supply |  |  |
| Degree of protection | IP54 in any mounting position NEMA 2, UL Enclosure Type 2 |  |  |
| EMC | CE according to 2004/108/EC |  |  |
| Certification | cULus according to UL 60730-1A and UL 60730-2-14 and CAN/CSA E60730-1:02 <br> Certified to IEC/EN 60730-1 and IEC/EN 60730-2-14 |  |  |
| Mode of operation | Type 1 |  |  |
| Rated impulse voltage | 0.8 kV |  |  |
| Control pollution degree | 3 |  |  |
| Ambient temperature | $-30 \ldots+50^{\circ} \mathrm{C}$ |  |  |
| Non-operating temperature | $-40 \ldots+80^{\circ} \mathrm{C}$ |  |  |
| Ambient humidity | 95\% r.h., non-condensating |  |  |
| Maintenance | Maintenance-free |  |  |

## Technical data

Dimensions / Weight

| Dimensions |
| :--- |
| Weight |
| Safety notes |

- The actuator is not allowed to be used outside the specified field of application, especially in aircraft or any other form of air transport.
- Assembly must be carried out by trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cable must not be removed from the device.
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.

| Mode of operation | The actuator is controlled with a standard modulating signal of DC $0 \ldots 10 \mathrm{~V}$ and travels to the <br> position defined by the control signal. Measuring voltage $U$ serves for the electrical display of the <br> damper position $0 \ldots 100 \%$ and as slave control signal for other actuators. |
| :--- | :--- |
| Parameterisable actuators | The factory settings cover the most common applications. Input and output signals and other <br> parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, <br> MFT-P. |
| Simple direct mounting | Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an <br> anti-rotation strap to prevent the actuator from rotating. |
| Manual override | Manual operation is possible with the pushbutton (the gearing latch remains disengaged as long <br> as the pushbutton is pressed or detented). |
| High functional reliability | Adjustable angle of rotation with mechanical end stops. <br> The actuator is overload-proof, requires no limit switches and automatically stops when the end <br> stop is reached. |

Home position When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement» switch, the actuator travels to the home position.

| Pos. direction of rotation switch | Home position |
| :--- | :--- |
| $\mathrm{D}_{1}^{0} \mathrm{Y}=0$ | cow |

The actuator then moves into the position defined by the control signal.

## Accessories

|  | Description | Data sheet |
| :---: | :---: | :---: |
| Electrical accessories | Auxiliary switch S..A.. | T2-S..A.. |
|  | Feedback potentiometer P..A.. | T2-P..A.. |
|  | PC-Tool MFT-P from version 3.3 | T2-MFT-P |
|  | Parameterising device MFT-H | T2 - MFT-H |
|  | Position sensor SGA24, SGE24 and SGF24 | T2-SG.. 24 |
|  | Digital position indication ZAD24 | T2-ZAD24 |
| Mechanical accessories | Various accessories (clamps, shaft extensions etc.) | T2-Z-SM..A.. |

## Electrical installation

| Wiring diagram |
| :--- | :--- |
| Notes |
| - Connection via safety isolating transformer! |
| - Other actuators can be connected in parallel. |
| Please note the performance data! |



## Cable colours:

1 = black
2 = red
3 = white
5 = orange

## Functions with basic values

Override control with AC 24 V with relay contacts


Remote control 0 ... $100 \%$


Master/Slave control (position-dependent)


Override control with AC 24 V with rotary control switch


## Minimum limit



Control with 4 ... 20 mA via external resistance

$\left.\begin{array}{c}(-) \\ (+)\end{array}\right\} 4 \ldots 20 \mathrm{~mA}$
(+) $\}$ DC $2 \ldots 10 \mathrm{~V}$


The $500 \Omega$ resistor converts the
4 ... 20 mA current signal to a voltage signal DC $2 \ldots 10 \mathrm{~V}$

Functions with basic values (Continued)

Position indication


Functional check


## Procedure

- Apply 24 V to connection 1 and 2
- Disconnect connection 3:
- For direction of rotation 0:

Actuator turns in the direction of

- For direction of rotation 1 :

Actuator turns in the direction of $\curvearrowright$

- Short circuit connections 2 and 3 :
- Actuator travels in the opposite direction


## Functions for actuators with specific parameters

Override control and limiting with AC 24 V
with relay contacts


Override control and limiting with AC 24 V with rotary switch

${ }^{1)}$ Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V


## Dimensions [mm]

Dimensional drawings


1) $\mathrm{CrNi}($ INOX $) 12 \ldots 20$

Operating controls and indicators

(1) Direction of rotation switch

Switching over: Direction of rotation changes
(2) Pushbutton and green LED display

Off: $\quad$ No voltage supply or malfunction
On: Operation
Press button: Switches on angle of rotation adaption followed by standard operation
(3) Pushbutton and yellow LED display

Off: Standard operation
On: Adaption or synchronising process active
Press button: No function
(4) Gear disengagement switch

Press button: Gear disengaged, motor stops, manual operation possible
Release button: Gear engaged, synchronisation starts, followed by standard operation
(5) Service plug

For connecting parameterising and service tools
Check voltage supply connection
a) (2) Off and (3) On
b) (2) Blinking and (3) Blinking
Check the supply connections.
b) (2) Blinking and (3) Blinking Possibly $\pm$ and $\tilde{\mp}$ are swapped over.

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AC 24 V / DC 24 V


SM24A..
AC $100 \ldots 240$ V


SM230A..


SM24A-S..


SM230A-S..


SM24AP5..



SM24A-MP..

AC $100 \ldots 240$ V


AC 24 V / DC 24 V (SM24A-V / VR..)


SM230A-V / VR..

