## Technical Instructions Document No. 155-517P25

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## SQM5... <br> Reversing Actuators

ISO 9000 and 14000 REGISTERED FIRM


## Description

SQM5... reversing actuators are used for the positioning of flow control valves, butterfly valves, dampers, or any application requiring rotary motion. The SQM5... actuators accommodate control input signals of 4 to $20 \mathrm{~mA}, 0$ to $135 \Omega, 0$ to $10 \mathrm{Vdc}, 0$ to 20 mA , position proportional and floating control. The available output signals include 4 to $20 \mathrm{~mA}, 0$ to $135 \Omega$, 0 to $10 \mathrm{Vdc}, 0$ to 20 mA , and 0 to $1000 \Omega$. SQM5 ... actuators are available with up to six internal, easily adjustable switches.

A selection of exchangeable circuit boards provide a variety of functions including auto/manual selector switch, manual forward/reverse toggle switch, zero and span adjustment, parallel or master/slave operation, split range control, input signal override, and selectable electronic linearization.

The SQM5... is engineered for precision. It is particularly well suited for applications requiring a high degree of modulating accuracy and repeatability. Drive shaft play is limited to $0.3^{\circ}$ with a modulating accuracy of 250 repositions through $90^{\circ}$ of travel.

The SQM5... actuator may be mounted in any position. A selection of mounting brackets and shafts provides installation flexibility and allows for the simple replacement of most competitive actuators.

## Features

- Modulating accuracy of 250 repositions through $90^{\circ}$
- Two limit switches, plus up to four internal auxiliary switches
- Fully closed "economy position" switch
- Drive shaft and cam drum disengagement clutches
- Auto/manual switch, manual control forward/reverse toggle switch
- UL, CSA approved 24 and 110 Vac versions
- CE approved 220 Vac versions
- Field reversible clockwise (cw) or counterclockwise (ccw) operation
- Various torque ratings and running times available
- Selection of field exchangeable single-ended and dual-ended shafts
- Mounting brackets to replace competitive actuators


## Features, Continued

- Connections for both base and face mounting
- Low hysteresis actuator and potentiometer gearing
- Externally visible position indication
- Selection of input and output signals
- Zero and span adjustment
- Field exchangeable circuit boards and potentiometers
- Electronic damper linearization function
- Split range and selectable parallel or master/slave operation
- Adjustable input signal override function


## Application

SQM5... actuators are uniquely suited for both industrial and commercial applications. The high level of accuracy permits precise modulating control of industrial process and process heating applications, often significantly enhancing performance and product quality.

In commercial and industrial burner applications requiring high turndown and reliable ignition, the auxiliary switches can be applied to create separate positions for burner ignition and low fire. In dual fuel applications, additional switches can be used to create separate high fire, low fire and ignition positions for each fuel. The economy position switch is used to drive the actuator to the full closed position when the burner is off.

In all applications, commissioning is simplified. Shaft and cam drum disengagement clutches allow for the quick manual alignment of the actuator shaft and switch cams. The forward/reverse toggle switch in combination with the auto/manual selector switch provides direct manual control.

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## Product Numbers

Table 1. Product Numbers for Pre-assembled Actuators.

| Torque ${ }^{1}$ | Running |  | Input Control Signals ${ }^{3}$ |  |  |  | Product Number |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| [lb-in] | $\begin{gathered} 90^{\circ} @ 60 \\ \text { Hzsec } \end{gathered}$ | 응 응 |  | $\begin{aligned} & \mathbb{G} \\ & \text { } \\ & \text { N } \\ & \dot{~} \end{aligned}$ | $\begin{aligned} & \mathrm{C} \\ & \text { N } \\ & \underset{\sim}{6} \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ | 110 V | 220 V | 24 V |
| 90 | 8 | ccw | x | x |  |  | SQM50.261R1G3 |  |  |
| 90 | 8 | cW | x | x |  |  | SQM50.261R1G3R |  |  |
| 90 | 8 | ccw | x |  |  |  | SQM50.264R1A | SQM50.264R2A |  |
| 90 | 8 | cW | x |  |  |  | SQM50.264R1A0R |  |  |
| 90 | 8 | ccw | x |  |  |  | SQM50.264R1A3 |  |  |
| 90 | 8 | cw | X | X |  |  | SQM50.264R1G3R |  |  |
| 90 | 8 | ccw | x | x |  |  | SQM50.264R1G4 |  |  |
| 140 | 12 | ccw | x | x |  |  | SQM50.361R1G3 |  |  |
| 140 | 12 | cw | x | x |  |  | SQM50.361R1G3R |  |  |
| 140 | 12 | ccw | X | X |  |  | SQM50.361R1G7 |  |  |
| 140 | 12 | ccw | X | X |  |  | SQM50.364R1G3 |  |  |
| 140 | 12 | cw | x | x |  |  | SQM50.364R1G3R |  |  |
| 140 | 25 | ccw | x |  |  |  | SQM50.461R1A |  |  |
| 140 | 25 | ccw | x |  |  |  | SQM50.461R1A3 |  |  |
| 140 | 25 | ccw | x | x |  |  | SQM50.461R1G3 |  |  |
| 140 | 25 | cw | X | x |  |  | SQM50.461R1G3R |  |  |
| 140 | 25 | ccw | X |  | X |  | SQM50.461R1H3 |  |  |
| 140 | 25 | ccw | x | x | x | x | SQM50.461R1Z3 |  |  |
| 140 | 25 | ccw | x | x | x | x | SQM50.461R1Z7 |  |  |
| 140 | 25 | ccw | x |  |  |  | SQM50.464R1A |  | SQM50.464R8A |
| 140 | 25 | cw | X |  |  |  | SQM50.464R1A0R |  |  |
| 140 | 25 | ccw | X |  |  |  | SQM50.464R1A3 |  |  |
| 140 | 25 | cw | X |  |  |  | SQM50.464R1A3R |  |  |
| 140 | 25 | ccw | x | x |  |  | SQM50.464R1G3 |  | SQM50.464R8G3 |
| 140 | 25 | cw | x | x |  |  | SQM50.464R1G3R | SQM50.464R2G3R |  |
| 140 | 25 | ccw | X | X |  |  | SQM50.464R1G7 |  |  |
| 140 | 25 | cW | X | X |  |  | SQM50.464R1G7R |  |  |
| 140 | 25 | ccw | X |  | x |  | SQM50.464R1H3 |  | SQM50.464R8H3 |
| 140 | 25 | ccw | x | x | X | x | SQM50.464R1Z3 | SQM50.464R2Z3 | SQM50.464R8Z3 |
| 200 | 25 | ccw | x |  |  |  | SQM53.464R1A |  |  |
| 200 | 25 | ccw | X |  |  |  | SQM53.464R1A3 |  |  |
| 200 | 25 | ccw | x | X |  |  | SQM53.464R1G3 |  |  |
| 200 | 25 | ccw | x | x |  |  | SQM53.464R1G7 |  |  |
| 200 | 25 | cw | x | x |  |  | SQM53.464R1G7R |  |  |
| 200 | 25 | ccw | x | X | X | x | SQM53.464R1Z3 | SQM53.464R2Z3 |  |
| 200 | 25 | ccw | x | x | X | X | SQM53.467R1Z3 |  |  |
| 200 | 25 | cw | x | X | X | X | SQM53.467R1Z3R |  |  |
| 200 | 25 | ccw | x |  |  |  |  | SQM53.467R2A3 |  |
| 310 | 37 | ccw | x |  |  |  | SQM56.564R1A |  |  |
| 310 | 37 | ccw | X | X |  |  | SQM56.564R1G4 |  |  |
| 310 | 37 | ccw | x | x |  |  | SQM56.564R1G7 |  |  |
| 310 | 37 | ccw | x |  | X |  | SQM56.564R1H4 |  |  |
| 310 | 37 | ccw | x | x | x | x | SQM56.564R1Z3 |  |  |
| 400 | 50 | ccw | X | X |  |  | SQM56.664R1G3 |  |  |
| 400 | 50 | ccw | X | X | X | x | SQM56.664R1Z3 |  |  |
| 400 | 50 | cw | x |  |  |  | SQM56.667R1A3R |  |  |
| 400 | 50 | ccw | x | x |  |  | SQM56.667R1G3 |  |  |
| 400 | 50 | cw | X | x |  |  | SQM56.667R1G7R |  |  |
| 400 | 50 | ccw | X | X | X | X | SQM56.667R1Z3 |  |  |

1. Torque will vary with the selection of the shaft. See Specifications.
2. Running time for $135^{\circ} \rightarrow$ multiply by 1.5 . For $50 \mathrm{~Hz} \rightarrow$ multiply by 1.2
3. SQM5x.xxxxxZx models also accept a 0 to 20 mA input signal.

Table 2. Product Numbers for Accessories.


## Product Number Identification Legend

For actuator identification only. To select product numbers for ordering, see Table 1.
Figure 1. SQM5... Product Number Identification Legend.


R Clockwise (when facing gear end. See Figure 6.)

## Installation and Operation Instructions

SQM5... actuators are sometimes shipped without the shaft installed. To install the selected shaft:

1. Loosen the two screws on the actuator cover corners. See Figure 2.
2. Lift the screws and raise the cover. See Figure 3.

## Shaft Installation



Figure 2.


Figure 3.
3. Each shaft is supplied with two washers and a "C" clip. See Figure 4. Using spreading pliers, remove the "C" clip and the washers from the shaft.


Figure 4.
4. Insert the "insert end" of the shaft into the "gear end" of the actuator.
5. Push the shaft until the "insert end" reaches just short of the brass bushing at the other end of the actuator.
6. Put one of the washers on the insert end of the shaft. See Figure 5.


Figure 5.
7. Line up the "shaft key" with the key slot on the "gear end" of the actuator and slide the shaft until the "insert end" is completely through the brass bushing.
8. Place the second washer onto the "insert end" of the shaft. Using spreading pliers, install the "C" clip.

## Rotational Direction Verification

Actuator model numbers that end with " R " are factory configured for clockwise (cw), minimum to maximum rotation when facing the gear end of the actuator, or counterclockwise (ccw) rotation when facing the other end of the actuator. The gear end of the actuator is the side opposite of the visual position indicator.

To field reverse the direction of rotation, see Service Guide, "Reversing Rotational Direction".

## Actuator Mounting

SQM5... actuators can be mounted in any orientation using the four 1/4"-20 UNC tapped holes located on the bottom corners of the actuator base. Optional base mounting brackets are available. See Table 2.
SQM5... actuators can also be face mounted using self tapping screws in combination with the various holes on the face of the actuator gear end.


Figure 6. Component Identification on the Cam Drum Side of the SQM5... Actuator.

## Switch Adjustment

See Figure 6.

All SQM5...actuators are factory wired with Switch I (maximum), Switch II (fully closed "economy position") and Switch III (minimum). The individual switch cams I, II, and III are factory set to $90^{\circ}, 0^{\circ}$ and $10^{\circ}$ respectively.

NOTE: The single switch cam pointers are used together with the black scales when configured for counterclockwise (ccw) operation.

The double switch cam pointers are used together with the red scales when configured for clockwise (cw) operation.

The individual switch cams can be adjusted by hand or with the use of the tool attached to the outside of the hinged switch terminal protection lid.

## Switch Adjustment, Continued

NOTE: If a potentiometer is installed, the adjustable range of the switches depends on the range of the potentiometer.
SQM5x.xxxxxAx actuators may be adjusted between $0^{\circ}$ and $160^{\circ}$.
SQM5x.xxxxxx3 actuators have a $90^{\circ}$ potentiometer and the switches must be adjusted only between 0 and $90^{\circ}$.
SQM5x.xxxxxx4 actuators have a $135^{\circ}$ potentiometer and the switches must be adjusted only between 0 and $135^{\circ}$.

## Shaft Adjustment

See Figure 6.

Cam Drum Adjustment
See Figure 6.
Position Indicating Dial Adjustment

The actuator shaft can be disengaged by pressing the silver shaft release button. The button is located above the grounding screw, under the hinged terminal protection cover, and to the right of the auto/manual switch. After pressing the shaft release button in and slightly upward, the shaft can be manually rotated. After the shaft has been manually aligned to the closed position, re-engage the shaft by pushing the shaft release button downwards.

Once the shaft has been set, the cam drum must be manually aligned by pressing and holding the black cam drum release button (see Figure 6). Rotate the cam drum until the " 0 " mark on the actuator position scale (left scale on the cam drum) is aligned with the gray actuator position indicating pointer.

The actual position of the SQM5... actuator is indicated by the gray actuator position indicating pointer (see Figure 6). The position is also displayed by the indicating dial through the housing's window. Ensure that the actuator position indicating dial is aligned with the actuator position scale. If necessary, rotate the dial in the clockwise direction.

## CAUTION:

Turning the dial in the counterclockwise direction may loosen the potentiometer locking screw.

## Wiring

Electrical Connection

SQM5... actuators are equipped with two removable conduit connection plates located on the upper corner of the gear housing. Each plate is provided with two threaded connections for $1 / 2^{\prime \prime}$ NPSM conduit connectors. The use of flexible stranded wire is recommended.

## Grounding

A

## CAUTION:

To avoid electro-magnetic interference, the SQM5... actuators must be grounded.

The ground terminal is located to the right of the auto/manual switch.
Disconnect the circuit board wire marked 51 during high voltage testing. Reconnect it to the grounding terminal after the test.

## Wiring Connections

AGA56.1... circuit boards.

See Figures 7 and 8.

NOTE: SQM5... actuators require a single source, single phase power supply.
Wiring connections vary depending on which AGA56.... circuit board is installed.

## Manual Operation

1. Set the AUTO/MAN switch in the MAN position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to the double terminal block, located on the left side of the gray switch housing.
4. Only terminal "L" must be to enable manual operation. The actuator can now be driven to the maximum position (switch cam I) or the fully closed "economy position" (switch cam II) by using the toggle switch located to the left of the AUTO/MAN switch.

## Automatic Operation

1. Set the AUTO/MAN switch in the AUTO position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to the double terminal block located on the left side of the gray switch housing.
4. Connect line voltage to terminal $A$ to drive the actuator in the opening direction.
5. Connect line voltage to terminal $Z$ to drive the actuator in the closing direction.

## CAUTION:

Do not power terminals $A$ and $Z$ simultaneously. Actuator damage will occur.


Figure 7. Basic Functional Diagram of AGA56.1...

## Wiring, Continued



Figure 8. AGA56.1A97 Terminal/Auto-Manual Board.

## AGA56.41/42/43...

Circuit Boards.
See Figures 9 and 10.

## Manual Operation

1. Set the AUTO/MAN switch in the MAN position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to terminal $N$.
4. Only terminal "L" must be powered to enable manual operation. The actuator can now be driven to the maximum (high fire) position (switch cam I) or the fully closed "economy position" (switch cam II) by using the toggle switch located to the left of the AUTO/MAN switch.

## Automatic Operation

1. Set the AUTO/MAN switch in the AUTO position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to terminal N .
4. Connect line voltage at all times to terminal $L$ to provide power to the electronic circuit board.
5. Connect line voltage to terminal LR to provide power when modulating. Connect line voltage to Terminal LR only after removing power on terminals $A$ and $Z$ (otherwise actuator damage may result).
6. Connect line voltage to terminal $A$ to drive the actuator to the maximum (high fire purge) position.
Once the maximum position is reached, terminal 11 (on switch I) will be energized to provide position feedback.
7. Connect power to terminal ZL to drive the actuator to the minimum (low-fire) position. Once the minimum position is reached, terminal 23 (on switch III) will be energized to provide position feedback. Adjustment of switch III will determine the low-fire stop position. Switch III (low fire) must be set at a higher position than switch II (fully closed). Terminal ZL may be energized only after removing power from terminals $A, Z, 13$, and LR.
8. Connect line voltage to terminal $Z$ to drive the actuator to the fully closed/economy position (switch II).
9. Connect the input control signal wires to the appropriate terminals. See Figure 9.

## CAUTION:

Do not power terminals $A$ and $Z$ simultaneously. Actuator damage will occur.

## Wiring, Continued



Figure 9. Basic Functional Diagram of AGA56.4...


Figure 10. AGA56.41/42/43... Terminal and Trim Potentiometer Boards.

## AGA56.9... Circuit Boards

See Figures 11 and 12.

## Manual Operation

1. Set the AUTO/MAN switch in the MAN position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to terminal N .
4. Only terminal "L" must be powered to enable manual operation. The actuator can now be driven to the maximum (high fire) position (switch cam I) or the fully closed "economy position" (switch cam II) by using the toggle switch located to the left of the AUTO/MAN switch.

## Automatic Operation

1. Set the AUTO/MAN switch in the AUTO position.
2. Connect ground to the screw located below the shaft release button.
3. Connect neutral to terminal N .
4. Connect line voltage at all times to terminal $L$ to provide power to the electronic circuit board.
5. Connect line voltage to terminal L1 to provide power when modulating. Connect line voltage to terminal L1 only after removing power on terminals A and Z (otherwise actuator damage may result).
6. Connect line voltage to terminal A to drive the actuator to the maximum (high fire purge) position. Once the maximum position is reached, terminal 11 (on switch I) will be energized to provide position feedback.
7. Connect power to terminal ZL to drive the actuator to the minimum (low-fire) position. Once the minimum position is reached, terminal 23 (on switch III) will be energized to provide position feedback. Adjustment of switch III will determine the low-fire stop position. Switch III (low fire) must be set at a higher position than switch II (fully closed). Terminal ZL may be energized only after removing power from terminals $A, Z, 13$, and $L R$.
8. Connect line voltage to terminal $Z$ to drive the actuator to the fully closed/economy position (switch II).
9. Connect the input control signal wires to the appropriate terminals. See Figure 11.

## CAUTION:

Do not power terminals $A$ and $Z$ simultaneously. Actuator damage will occur.

## Wiring, Continued



Figure 11. Basic Functional Diagram of AGA56.9...


AGA56.9A...

Figure 12. AGA56.9... Terminal and Trim Potentiometer/Jumper Board.

## Modulation Adjustment

See Figures 10 and 12.

The blue trim potentiometers allow the adjustment of the minimum (zero) and maximum (span) positions.
The factory setting of the MIN trim potentiometer is rotated fully counter clockwise. The factory setting of the MAX trim potentiometer is rotated fully clockwise.

Set the OPE/MAX/MIN slide switch to MIN. The blue MIN trim potentiometer can now be gently adjusted to the required minimum position. Return the OPE/MAX/MIN slide switch to OPE for operation.

NOTE: Do not set switch cam I higher than:
$90^{\circ}$ when using feedback potentiometers ASZxx. 30
$135^{\circ}$ when using feedback potentiometers ASZxx. 33
Set the OPE/MAX/MIN slide switch to MAX. The blue MAX trim potentiometer can now be gently adjusted to the required maximum position. Return the OPE/MAX/MIN slide switch to OPE for operation.


Figure 13. Switch cam and Trim Potentiometer Setting.

NOTE: The actual minimum and maximum modulating range is determined either by the setting of the MIN and MAX trim potentiometers or the setting of switch cam III (Minimum) and switch cam I (Maximum). The actuator can never modulate outside of the range set by switch cam I and III. If the MIN and MAX trim potentiometers are set outside the setting range of switch cams I and III, then the switch cam settings determine the modulating range. If a soft stop is desired, the modulating range can be defined by the trim potentiometers if the MIN and MAX trim potentiometers are set inside the setting range of switch cams I and III. See the example in Figure 13.

## Cover Installation

1. Lift the two screws on the cover corners and slide the cover end into the grooves at the gear end of the actuator. See Figure 14.
2. Press the cover into place and then press the screws inward and tighten. See Figure 15.


Figure 14.


Figure 15.

Features of SQM5x.xxxxxZX Actuators

Multiple Input Signals

SQM5xx.xxxxxZx actuators contain the AGA56.9A... multi function circuit board. This circuit board provides the following features:

The AGA56.9A... circuit board accepts the following input signals:

## Line voltage

- Power to A drives the actuator open to the setting of switch cam I (Maximum).
- Power to ZL drives the actuator closed to the setting of switch cam III (Minimum).
- Power to $Z$ drives the actuator closed to the setting of switch cam II (Economy).
- $\mathbf{4}$ to 20 mA (Signal to Y3, common to M)
- $\mathbf{0}$ to $135 \Omega$ (Slide wire signal to Y 0 , potentiometer connected to M and U 4 )
- 0 to 10 Vdc (Signal to Y1, common to M)
- $\mathbf{0}$ to $\mathbf{2 0} \mathbf{~ m A ~ ( S i g n a l ~ t o ~ Y 2 , ~ c o m m o n ~ t o ~ M ) ~}$


## Multiple Output Signals

The AGA56.9A... circuit board provides the following output signals:

- 4 to 20 mA (Signal from U3, common to M)
- 0 to $\mathbf{1 0 V d c}$ (Signal from U1, common to M)
- $\mathbf{0}$ to $\mathbf{2 0 m A}$ (Signal from U2, common to M)

Double potentiometers ASZ22... provide additional output signals.

## Electronic Linearization Function

## Input Signal Override

## Parallel Operation

## Master/Slave Operation

## Split Ranging

Butterfly valves have non-linear flow characteristics. Near the fully closed position, a small change in the valve's position will produce a very large change in flow. Near the fully open position, a large position change will produce a relatively small change in flow.

The linearization function is intended to minimize the initial steep flow curve characteristics of a typical butterfly valve. The linearization function is enabled when Jumper J 1 is in position 1 (upper position). Consequently, the actuator will make smaller rotational movements when subjected to lower input signals and larger rotational movements when subjected to higher input signals.

For example (based on a $90^{\circ}$ modulating range), a change in input signal from 4 to 8 mA will cause a rotational movement of $11.25^{\circ}$. An equal change from 16 to 20 mA will cause a rotational movement of $45^{\circ}$. Thus, with the linearization function enabled, the change in flow is closely proportional to the change in input signal.

The linearization function is disabled when Jumper J 1 is in position 2 (lower position). When disabled, the rotational movement of the shaft is proportional to the input signal.

Line voltage to terminal $P$ will drive the actuator to a pre-set adjustable position, overriding all modulating input signals. Use the potentiometer marked POS to adjust the override position to any setting within the setting range of switch cams I and III.

NOTE: The input signal override can also be used for the ignition position of burners if different from the low fire position.

Set Jumper J2 in position 1 (upper position) to configure the actuator for parallel operation. Input signals Y0, Y1, Y2 or Y3 are directly shunted to output signals U1, U2 and U3. All output signals are available regardless of which input signal is applied.

Set J2 in position 2 (lower position) to configure the actuator for master/slave operation. The output signals U1, U2 and U3 reflect actual shaft position.

AGA56.9... circuit boards have a modulating signal shift feature which can be used for split ranging. If no signal is present on $\mathrm{Y} 0, \mathrm{Y} 1, \mathrm{Y} 2$ or Y 3 , the actuator will modulate through the full rotational range in response to a 12 to 20 mA signal applied at ZF . If a maximum signal is present on $Y 0, Y 1, Y 2$, or $Y 3$, then the actuator will modulate through the full rotational range in response to a 4 to 12 mA signal applied at ZF . (Maximum signal can be easily achieved by bridging terminals U4 and Y0.) See Figure 16.

NOTE: It is possible to configure the actuator for split range operation 12 to 4 mA and 20 to 12 mA . Consult your authorized Siemens Building Technologies combustion products sales representative for details.


Figure 16. Split Ranging.
Features of
SQM5x.xxxxxGx,
SQM5x.xxxxx $\mathrm{H} x$,
SQM5x.xxxxxKx
Actuators

## Input Signals

## Output Signals

Features of SQM5x.xxxxxAx Actuators

## Input Signals

## Output Signals

## Service Guide

## Reversing Rotational Direction

SQM5x.xxxxxGx actuators contain the AGA56.41A... circuit board with terminals Y - and $\mathrm{Y}+$ for 4 to 20 mA modulating input.

SQM5x.xxxxxHx actuators contain the AGA56.42A... circuit board with terminals Y, M and $U$ for 0 to $135 \Omega$ modulating input.

SQM5x.xxxxxKx actuators contain the AGA56.43A... circuit board with terminals Y and M for 0 to 10 Vdc modulating input.

The AGA56.4xA... circuit boards accept the following additional input signal:

## Line voltage

- Power to A drives the actuator open to the setting of switch cam I (Maximum).
- Power to $Z$ drives the actuator closed to the setting of switch cam II (Economy).
- Power to ZL drives the actuator closed to the setting of switch cam III (Minimum).

The AGA56.4xA... circuit boards do not provide output signals. Install a double potentiometer ASZ22...to obtain a 0 to $1000 \Omega$ actuator position output signal.

The AGA56.1A97... circuit boards accept the following additional input signal:

## Line voltage

- Power to A drives the actuator open to the setting of switch cam I (Maximum).
- Power to $Z$ drives the actuator closed to the setting of switch cam II (Economy).
- Power to switch III, terminal 3 drives the actuator to the setting of switch cam III (Minimum).
The AGA56.1A97 circuit board provides no output signals. Install an ASZ... potentiometer to obtain an actuator position output signal.



## WARNING:

Disconnect the power supply to the actuator before performing any service functions.

1. Disconnect the wires marked 21 and 12 , and reverse.
2. Adjust all switch cams to the desired settings (see Figure 6):

- For CCW rotation use the black cam drum scales and the single switch cam pointers.
- For CW rotation, use the red cam drum scales and the double switch cam pointers.

NOTE: Press and hold the black cam drum release button to rotate the cam drum. This will give easy access to the switch cams and a better view of the cam drum scales.
If no potentiometer ASZ... is installed, the reversing procedure is complete. If a potentiometer ASZ... is installed, complete Steps 3 through 9.


Figure 17a. Reversing Rotational Direction on the ASZ Potentiometer (Gear Models).
3. Disconnect the blue and brown wires from the terminal block located on the ASZ... potentiometer circuit board and reverse. The black wire remains connected to the middle terminal. See Figures 17 and 17a.
4. Remove the white plastic actuator position-indicating dial by gently pulling while rotating in the clockwise direction. See Figure 6.
5. The actuator position indicating pointer, located near the actuator gear end of the cam drum, must point to the " 0 " mark on the actuator position scale (scale on the cam drum nearest to the actuator gear end). Press and hold the black cam drum release button while manually rotating the cam drum.
6. Loosen the black potentiometer cam attachment screw approximately one turn. Gently wedge a small screwdriver between the potentiometer and the gray plastic housing. Gently twist the screwdriver until the potentiometer releases from the cam drum shaft.
7. Change potentiometer end position:

- Manually rotate the potentiometer position indication pointer exactly to the other end mark (see Figure 17).
- Gear models (see Figure 17a):

For clockwise rotation, manually rotate the potentiometer gear until the white line next to the "0" mark on the potentiometer gear face is exactly in alignment with the potentiometer gear alignment pointer.
For counterclockwise rotation, manually rotate the potentiometer gear until the white line next to the " 1 " mark on the potentiometer gear face is exactly in alignment with the potentiometer gear alignment pointer

## Reversing Rotational

 Direction, Continued8. Firmly tighten the black potentiometer cam attachment screw while manually holding the potentiometer position indication pointer in alignment. Check the alignment again.
9. Re-install the white actuator-indicating dial by gently pressing it onto the potentiometer cam attachment screw. Align scale position "0" on the actuator position indicating dial with the dial pointer by rotating the dial in the clockwise direction to avoid loosening the potentiometer cam attachment screw.

## Shaft Installation

Preparation Before Circuit Board Installation

See Installation and Operation Instructions.

AWARNING:

Disconnect the power supply to the actuator before replacing the circuit boards.

The black circuit board mounting bracket, installed on the inside base of the SQM5... actuator has four vertical, slotted circuit board supports. Remove the terminal section and circuit board(s) from the mounting bracket.

The actuator motor capacitor is attached to the lower section of the gray plastic switch housing using snap-on holding clips. Gently pull the capacitor forward until it unclips and temporarily place it on top of the gear housing. See Figure 18.


Figure 18.


## CAUTION:

Do not disconnect any capacitor wiring.

1. Remove the AGA56.41/42/43... circuit board from the packaging. The circuit board is shipped as one board.
2. Separate the board at the perforation by holding the circuit board at both ends and gently bending the board until it separates.
3. Move the terminal section containing the auto/manual switch to the opposite end of the base circuit board.
4. From the switch housing side of the actuator, guide the base circuit board into the bottom of the circuit board mounting bracket. See Figure 19.


Figure 19.

AGA56.41/42/43
Circuit Board Installation, Continued
5. Re-install the actuator motor capacitor. See Figure 20.
6. Gently guide the terminal section into the support slots and slide the terminal board downward until both supports snap into place. Ensure that the four brown wires and the flat white connector cable which connect the two circuit boards are positioned correctly in their respective corners allowing the board to freely slide into place without pinching either wire. See Figure 21.
7. Connect the bundled blue, black and brown potentiometer wires to the terminal block located on the ASZ... potentiometer circuit board. See Potentiometer Installation.


Figure 20.


Figure 21.

AGA56.41/42/43
Circuit Board Installation, Continued
8. Make the following connections to the actuator: See Figure 22.
a. Connect the wire, marked "1" from the circuit board to switch I, terminal 1.
b. Connect the wire, marked " 2 " from the circuit board to switch II, terminal 2.
c. Connect the wire, marked " 3 " from the circuit board to switch III, terminal 3.
d. Connect the wire, marked "13" from the circuit board to switch III, terminal 13.
e. Connect the blue neutral wire marked " N " to the double terminal block located on the outer end of the switch housing
f. Connect the grounding wire marked " 51 " to the ground terminal located to the right of the auto/manual switch.


Figure 22.

AGA56.9A...
Circuit Board Installation

1. Remove the ASZ... potentiometer if already installed on the SQM5... actuator. See Potentiometer Removal/Installation Instructions.
2. Remove the AGA56.9A... circuit boards from the packaging. The three separate AGA56.9A circuit boards are shipped in a circuit board mounting bracket.
3. Remove the two upright circuit boards from the mounting bracket by gently pulling aside the vertical supports and sliding the boards upward. Remove the base circuit board from the bottom of the mounting bracket. Discard the shipping mounting bracket.

AGA56.9A...
Circuit Board Installation, Continued
4. Guide the base circuit board from the switch housing side of the actuator into the bottom of the circuit board mounting bracket. See Figure 23.
5. Re-install the actuator motor capacitor. See Figure 24.
6. Gently guide the terminal board into the support slots and slide the terminal board downward until both supports snap into place. See Figure 25.
7. See Figure 26 and make the following connections to the actuator:
a. Connect the wire, marked " 1 " from the circuit board to switch I, terminal 1.
b. Connect the wire, marked " 2 " from the circuit board to switch II, terminal 2. Connect the white wire, marked " 3 " from the circuit board to switch III, terminal 3.
c. Connect the wire, marked " 13 " from the circuit board to switch III, terminal 13.
d. Connect the neutral wire, marked " N " to the double terminal block located on the outer end of the switch housing.
e. Connect the grounding wire marked "51" to the ground terminal located to the right of the auto/manual switch.


Figure 23.


Figure 24.


Figure 25.

AGA56.9A...
Circuit Board Installation, Continued
8. Gently guide the L-shaped circuit board containing the three blue trim potentiometers into the vertical support slots located on the cam drum side of the actuator. See Figure 27.
9. Slide the circuit board downward until both supports snap into place. Install the ASZ... potentiometer. (See Potentiometer Removal/Installation Instructions.)
10. Connect the bundled blue, black and brown potentiometer wires to the terminal block located on the ASZ... potentiometer circuit board.


Figure 26.


Figure 27.

AGA56.1A97
Circuit Board Installation

1. Install the AGA56.1A97 circuit board into the two slotted circuit board supports located on the switch housing side of the actuator.
2. Gently guide the AGA56.1A97 circuit board into the support slots and slide the board downward until both supports snap into place.
3. Make the following connections to the actuator:
a. Connect the wire, marked "1" from the circuit board to switch I, terminal 1.
b. Connect the wire, marked " 2 " from the circuit board to switch II, terminal 2.
c. Connect the wire, marked " 13 " from the circuit board to switch III, terminal 13.

## Potentiometer Removal

## Potentiometer Installation

9. Remove the white plastic actuator position-indicating dial by gently pulling while rotating in the clockwise direction. See Figure 6.
10. Disconnect the blue, black and brown wire from the potentiometer terminal block. See Figure 17.
11. Remove the silver potentiometer alignment screw.
12. Loosen the black potentiometer cam attachment screw approximately one turn.
13. Gently wedge a small screwdriver between the potentiometer and the gray plastic housing.
14. Carefully twist the screwdriver until the potentiometer releases from the cam drum shaft. Remove the ASZ... potentiometer.
15. Install the new $A S Z \ldots$ potentiometer by gently sliding the bushing over the cam drum shaft.
16. Align the potentiometer alignment screw hole with the hole in the gray plastic housing and install the potentiometer alignment screw. See Figures 17 and 17a.
17. The actuator position indicating pointer, located near the actuator gear end of the cam drum, must point to the "0" mark on the actuator position scale. See Figure 6. The scale is located on the cam drum nearest to the actuator gear end. Press and hold the black cam drum release button while manually rotating the cam drum.
18. If installing a potentiometer without gear, manually rotate the potentiometer pointer until the pointer is exactly in the "min" position. See Figure 17. Firmly tighten the black potentiometer cam attachment screw while manually holding the potentiometer pointer in alignment. Check the alignment again.
19. If installing a gear model potentiometer, manually rotate the potentiometer gear until the white line next to the " 0 " or " 1 " mark on the potentiometer gear face is exactly in alignment with the potentiometer gear alignment pointer. See Figure 17a. For counterclockwise (ccw) operation the line beside the " 1 " mark must exactly align with potentiometer gear alignment pointer. For clockwise (cw) operation the line beside the " 0 " mark must exactly align with potentiometer gear alignment pointer. Firmly tighten the black potentiometer cam attachment screw while manually holding the potentiometer gear in alignment. Check the alignment again.
20. Connect the bundled blue, black and brown potentiometer wires to the terminal block located on the ASZ... potentiometer board. See Potentiometer Installation and Figures 17 and 17a.
21. Re-install the white actuator-indicating dial by gently pressing it onto the potentiometer cam attachment screw. Align scale position " 0 " on the actuator position indicating dial with the dial pointer by rotating the dial in the clockwise direction to avoid loosening the potentiometer gear attachment screw. See Figure 6.

## Specifications

## SQM5... Reversing

 ActuatorSQM5... Reversing actuator
Agency approvals
Operating voltage

Operating frequency
Power consumption
Type of motor
Duty cycle
Torque
Maximum shaft torque
AGA58. 1
AGA58.2
AGA58.3
AGA58.4
AGA58.7
Timings
Rotational range of operation
SQM5x.xxxxxA models
SQM5x.xxxxxx 3 models
SQM5x.xxxxxx4 models
SQMSx.xxxxxx6 models
Direction of rotation
Shaft
Shaft disengagement
Number of auxiliary switches
Limit switches
Electrical rating of auxiliary switches
Mounting position
Ambient operating temperature
Shipping temperature
NEMA ratings
Connections
Switches Spade connectors
Boards
Dimensions
Weight
Housing
Enclosure (cover)
Motor
Disengagements

UL, CSA, CE
$24 \mathrm{Vac}+10 \%-15 \%$
$110 \mathrm{Vac}-15 \%$ to $120 \mathrm{Vac}+10 \%$
220 Vac-15\% to 240 Vac $+10 \%$
50 to 60 Hz
20 VA
Reversing synchronous motor
100\%
See Table 1.
$90 \mathrm{lb}-\mathrm{in}$
$200 \mathrm{lb}-\mathrm{in}$
$220 \mathrm{lb}-\mathrm{in}$
$270 \mathrm{lb}-\mathrm{in}$
$400 \mathrm{lb}-\mathrm{in}$
See Table 1.
$0^{\circ}$ to $160^{\circ}$
$0^{\circ}$ to $90^{\circ}$
$0^{\circ}$ to $135^{\circ}$
$0^{\circ}$ to $160^{\circ}$
Reversible
Selectable. See Table 2.
Custom versions on request
Independent, cam and drive shaft
4 switches (standard, maximum 6)
2 switches (standard)
7.5 (3) A, 250 Vac

Optional
$-5^{\circ} \mathrm{F}$ to $140^{\circ} \mathrm{F}\left(-20^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$
$-58^{\circ} \mathrm{F}$ to $140^{\circ} \mathrm{F}\left(-50^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$
NEMA 1, 2, 3, 3R, 3S, 5, 12, and 13

Screwed and spade connectors
See Figures 28 through 31.
$7.3 \mathrm{lb}(3.3 \mathrm{~kg})$
Aluminum pressure die casting
Lexan
Lock resistant
Manual for drive and cam shaft


## Specifications, continued

AGA56.43A...

## AGA56.9A

## ASZ... Potentiometers

AGA56.43A... Electronic circuit boards

Input signa
Impedance
Voltage input
AGA56.9A... Multi function electronic circuit boards
Operating voltage

Operating frequency
Input signals

Impedance
Current input
Voltage input
Output signals

Max output load
Current output
Voltage output
Zero adjustment
Span adjustment
Split ranging (SHIFT)
Input signal override (POS)
Ambient operating temperature
Shipping temperature
Auto/manual switch
Manual toggle switch
Weight
ASZ... Potentiometers
Versions
Resistor values
Hysteresis

Same specifications as AGA56.41A except:
0 to 10 Vdc
$\geq 100 \mathrm{~K} \Omega$
Single potentiometer
ASZ... (1000 ohm) is required
24 Vac $+10 \%-15 \%$
110 Vac -15\% to $120 \mathrm{Vac}+10 \%$
$220 \mathrm{Vac}-15 \%$ to $240 \mathrm{Vac}+10 \%$
50 to 60 Hz
4 to 20 mA
0 to 20 mA
0 to 10 Vdc
0 to 135 ohm
$\leq 300 \Omega$
$\geq 100 \mathrm{~K} \Omega$
4 to 20 mA
0 to 20 mA
0 to 10 Vdc
<600 ohm
> 1.5 K ohm
MIN: 0 to 75\%
MAX: min-100\%
4 to 20 mA on terminal ZF
Line voltage (... Vac) on terminal P adjust with POS potentiometer
$-5^{\circ} \mathrm{F}$ to $140^{\circ} \mathrm{F}\left(-20^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$
$-58^{\circ} \mathrm{F}$ to $140^{\circ} \mathrm{F}\left(-50^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$
2-position switch
3-position switch
$0.7 \mathrm{lb}(0.33 \mathrm{~kg})$

Single and double potentiometer
See Table 2 and Data Sheet 7921.
< 0.3\% related to drive shaft

## Dimensions

The first dimension given is measured in inches. Millimeters are shown in parentheses.


Figure 28. SQM5x.xxxRxx Dimensions.

## Dimensions, Continued



Figure 29. Mounting Bracket AGA57.3.


Figure 30. AGA57.4 Mounting Bracket.

## Dimensions, Continued



Figure 31. Shaft Dimensions.
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